

Sviluppo e test del primo livello di trigger del progetto spaziale JEM-EUSO

Development and testing of the first trigger level of the spatial project JEM-EUSO



Candidato: **Gregorio Suino**

Relatore: **Mario Edoardo Bertaina**

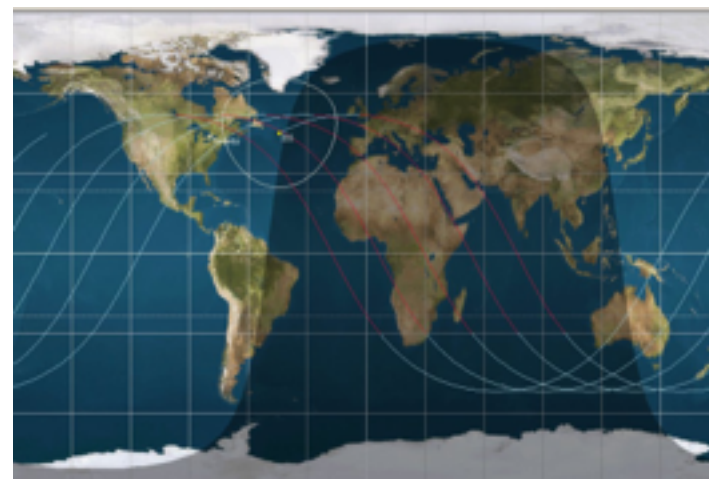
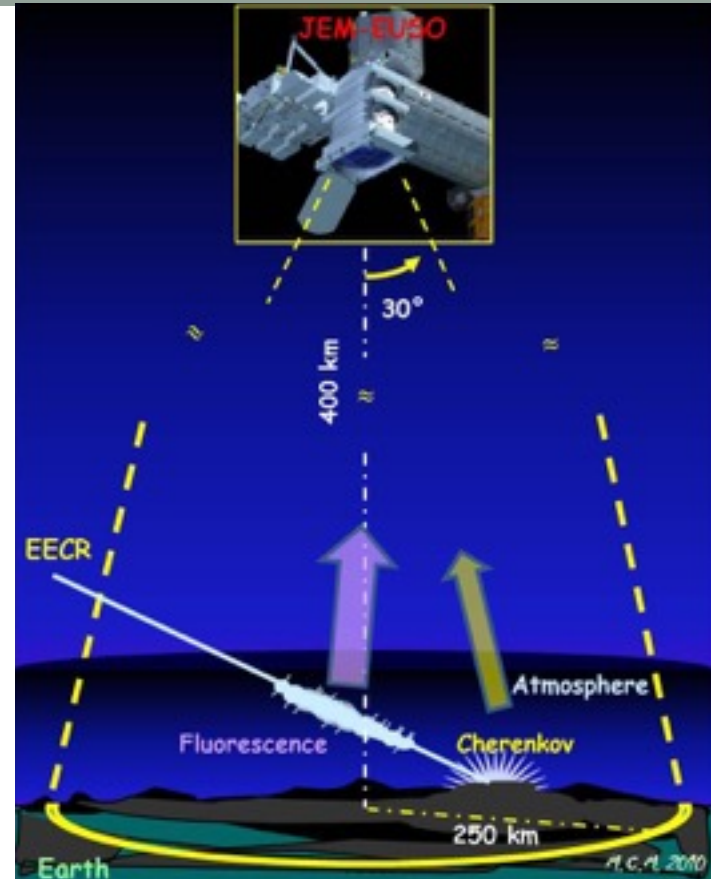
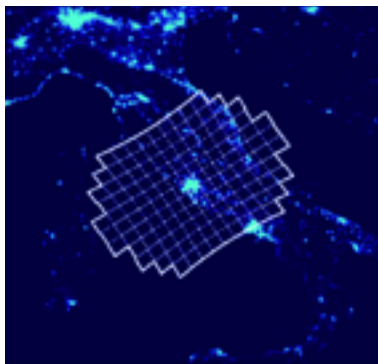
Summary

- JEM-EUSO experiment
- JEM-EUSO 1st level trigger logic
- Test of trigger logic at TurLab
- Path finder: EUSO-Balloon
- Offline analysis of trigger logic using EUSO-Balloon data
- Upgrades of trigger logic

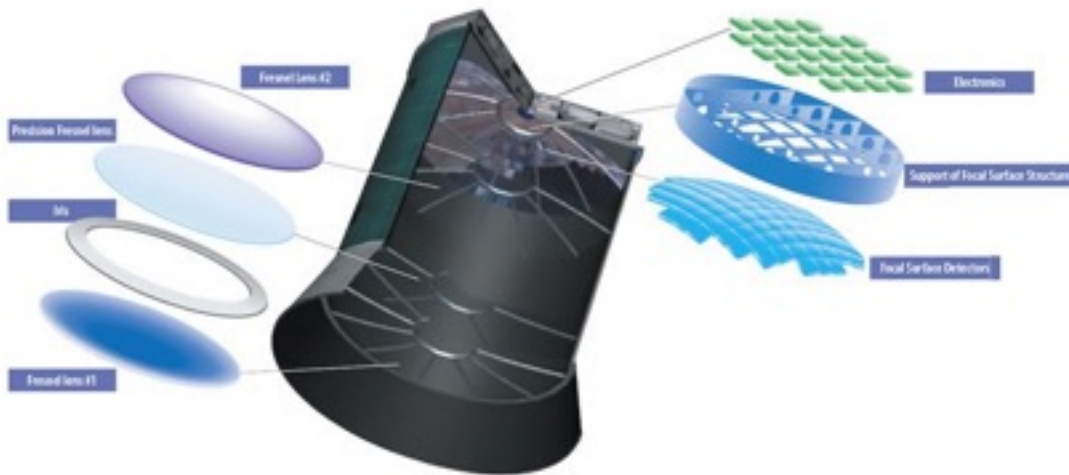
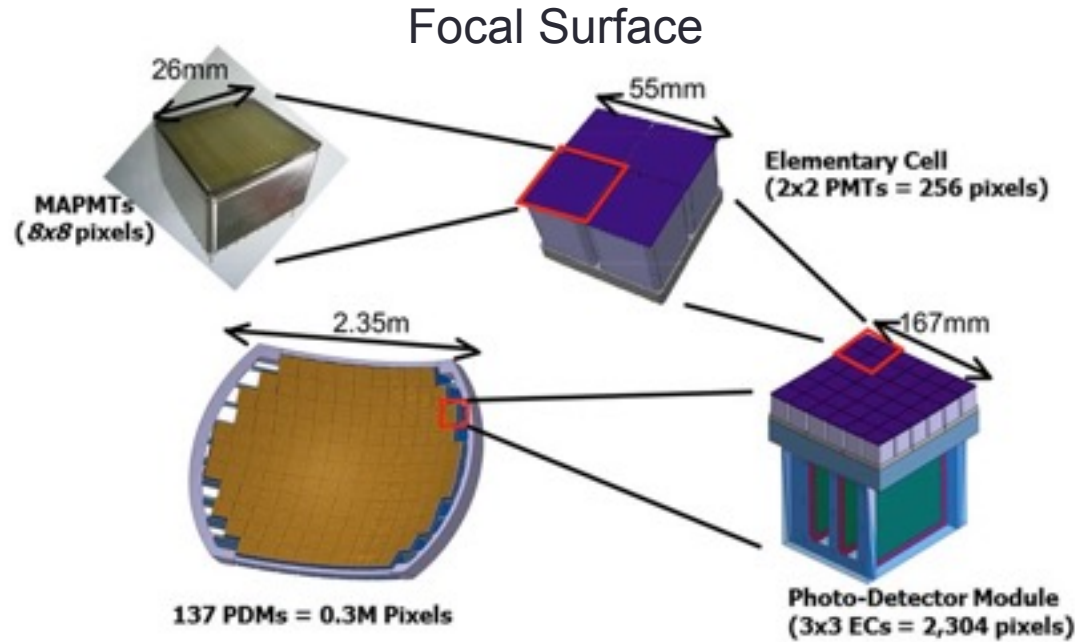
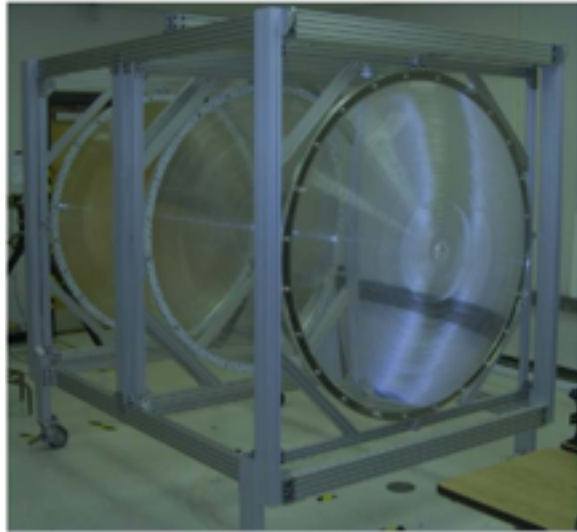
JEM-EUSO

Detection of cosmic ray of $E > 5 \times 10^{19}$ eV

- Orbit height: 400 km
- Orbit period: 90'
- Speed of International Space Station: 7 km/s
- Pixel covered area at the ground: 500×500 m²
- Single photon counting
- Gate Time Unit (GTU): 2,5 μ s
- Standard background (BCKG) on ocean :
500 $\text{phe} \cdot \text{m}^{-2} \cdot \text{ns}^{-1} \cdot \text{sr}^{-1} \sim 1 \text{ phe} \cdot \text{pix}^{-1} \text{GTU}^{-1}$



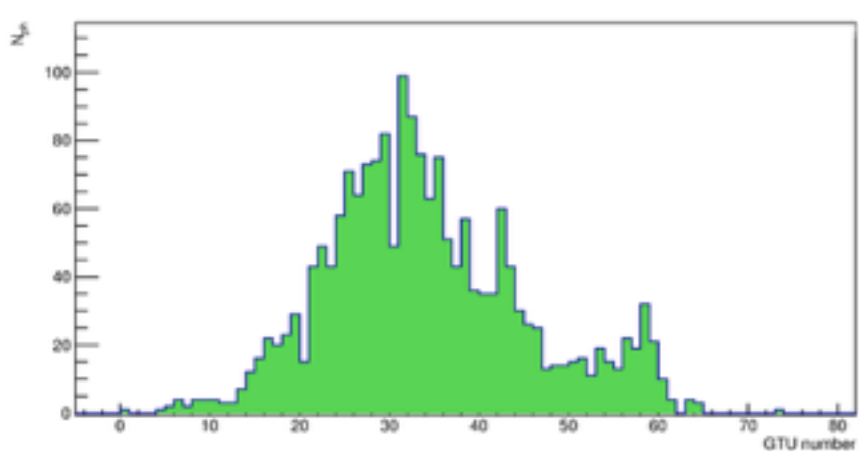
The JEM-EUSO detector



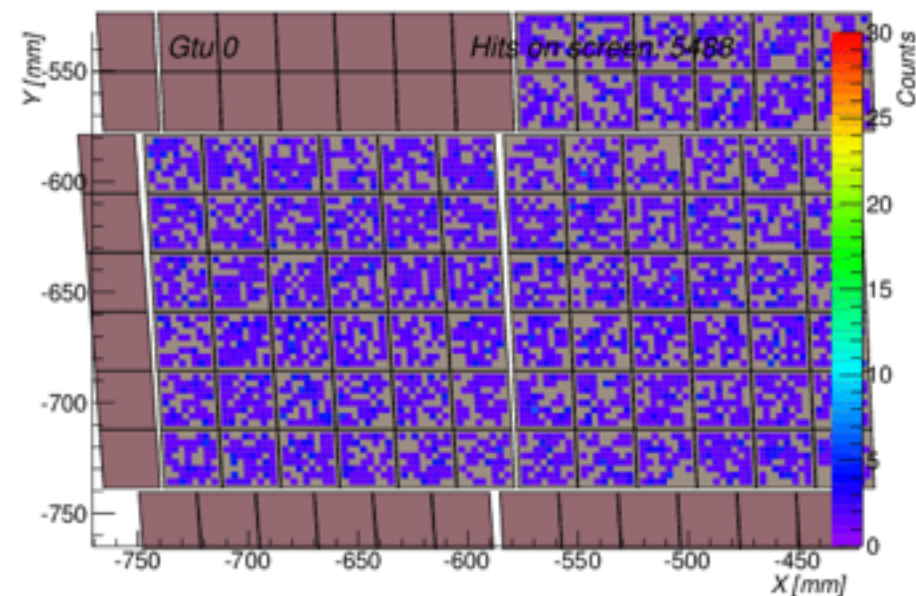
First Target:

Extreme Energy Cosmic Ray (EECR) & Extensive Air Shower (EAS):

- Duration: $\sim 200 \mu\text{s}$
- Intensity: $5 - 10 \text{ counts} \cdot \text{pix}^{-1} \text{GTU}^{-1}$



Total number of counts due to a Cosmic Ray



Simulation of a 2×10^{20} eV EECR as detected by JEM-EUSO

Duration and intensity of different light sources

Source	Duration	Intensity [ph·pix ⁻¹ ·GTU ⁻¹]	Extension on focal surface
Cosmic Ray	~ 200 μs	25 – 60	3×3 pixels box
Lightning	1 – 10 ms	10 ³ – 10 ⁶	PDM - FS
Meteor	100 ms – 2 s	500 – 2500	MAPMT
City	~ 1 s	50 – 500	Some pixels - FS
BCKG		~1	FS

Trigger

- **Purpose:** on board and real time data reduction
- **GTU:** $2,5 \mu\text{s}$ (4×10^5 GTU/s) roughly corresponds to the time a light signal takes to cross the pixel's diagonal for an horizontal shower (0.75 km)
- **Amount of data:** 1 Tb/s

$$3,2 \times 10^5 \text{ pixel} \times 4 \times 10^5 \text{ GTU} / \text{s} \times 8 \text{ bit} / \text{pixel} \approx 1 \text{ Tb} / \text{s}$$

- **Available telemetry resources:** 300 kb/s
- **Needed data reduction:** 3×10^6 (1st + 2nd TL)

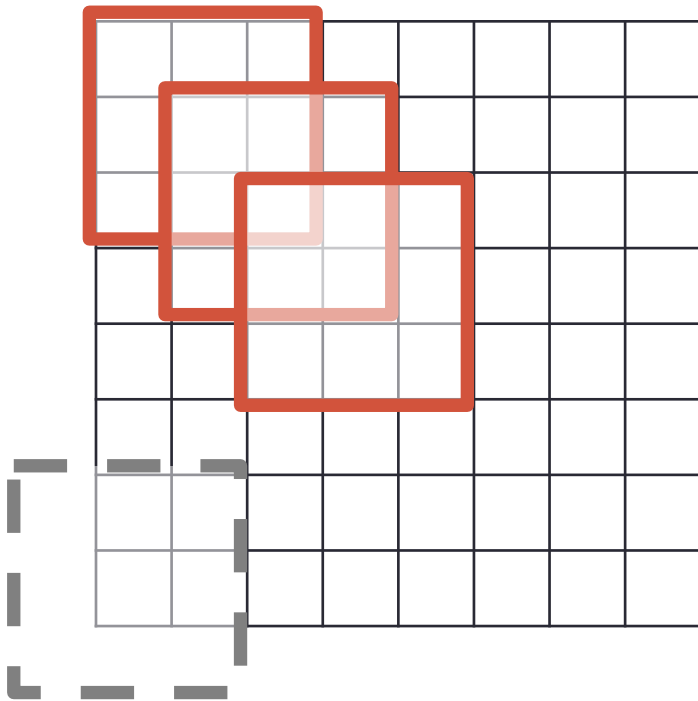


1st Level Trigger: persistency tracking trigger (PTT)

- **main objective:** reduce the rate of fake triggers to **1Hz/EC** (9 Hz/PDM)
- **Cosmic ray shower:**
 - generates persistent and spatially confined signal excesses above BCKG
 - the signal excess lasts at most 36 GTUs in the EC FoV
- **1st Level Trigger:**
 - operates at EC level
 - works with 128 GTU blocks
 - searches for signal excesses in 3×3 boxes lasting a few GTUs.



Trigger logic: the 3×3 pixel box



- 3×3 pixel boxes.
- 36 boxes in total in each MAPMT.
- Boxes work independently.
- They partially overlap.
- They cover the entire MAPMT.
- Different MAPMTs do not share any box.

Trigger logic

- N_{C1} : photoelectron counts of each pixel
- N_{C2} : photoelectron counts excess calculated over pixel threshold n^{pix}

$$N_{C2} = N_{C1} - (n^{pix} - 1)$$

- Excesses on the 3×3 boxes summed up over a number of GTU N_{pst}
- Trigger is issued if the summation is greater or equal than a settled threshold n^{box}

$$\sum_{i=1}^{N_{pst}} \sum_{3 \times 3} N_{C2} \geq n^{box}$$

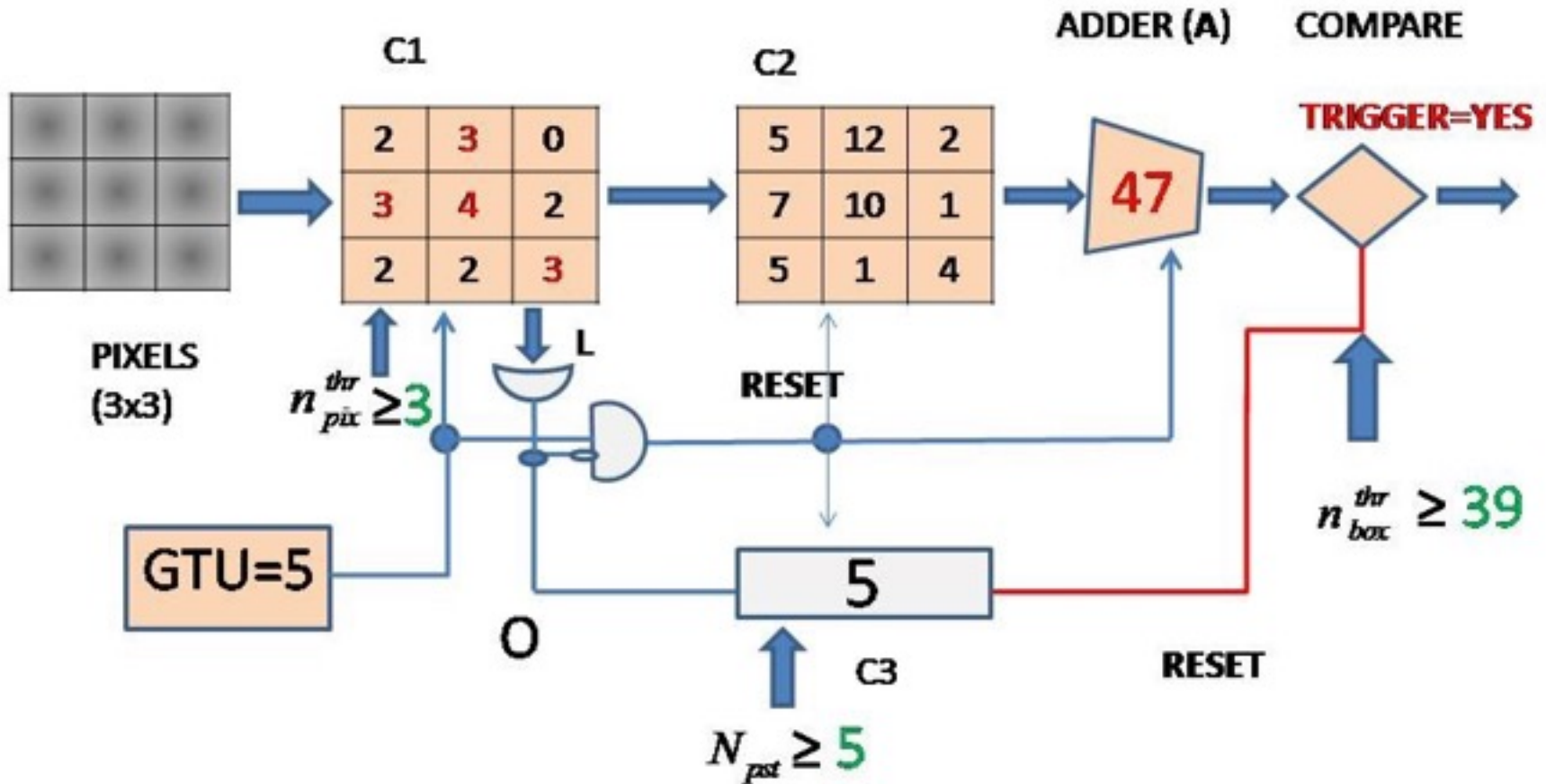
Example parameters

n^{pix}	3
n^{box}	39
N_{pst}	5

Example now!

Example: trigger is issued

EXAMPLE: TRIGGER IS ISSUED



$$N_{C2} = N_{C1} - n_{pix}^{thr} + 1$$

Thresholds

	BCKG	n^{pix}	n^{box}	BCKG	n^{pix}	n^{box}
	0,5	1	26	3,5	5	68

$500 \frac{phe}{m^2 \cdot ns \cdot sr}$ →	1,0	2	31	4,0	6	64

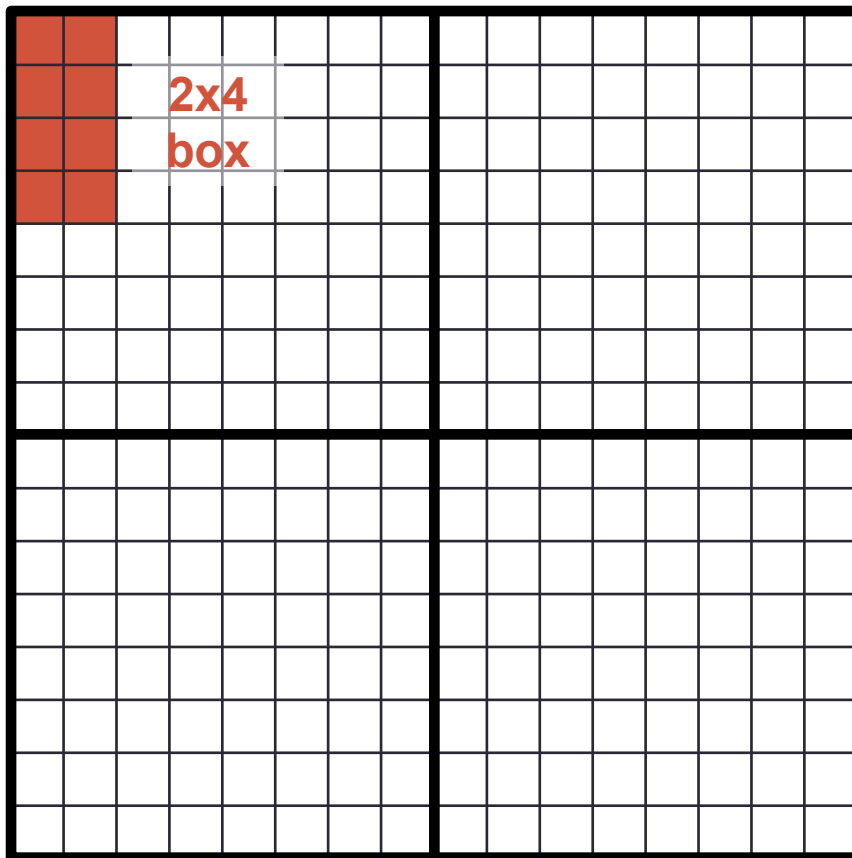
	1,5	2	53	4,5	7	61

	2,0	3	54	5,0	7	78

	2,5	4	50	5,5	8	64

	3,0	5	46	6,0	8	78 ←
						$3000 \frac{phe}{m^2 \cdot ns \cdot sr}$

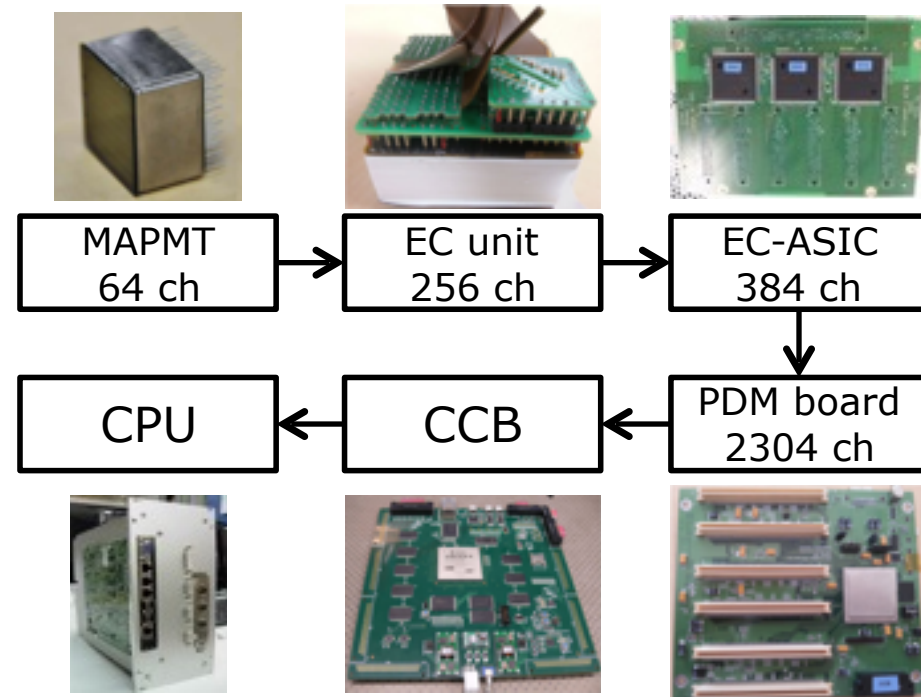
Dynamic threshold setting



- The EC subdivided into 32 2x4 boxes
- 2x4 pixels = 1x2 km² area at the ground
- no overlap
- Using a 128 GTU average the relative error is of the order of 3%
- threshold set according to the maximum average background every 128 GTU

Implemented, now testing

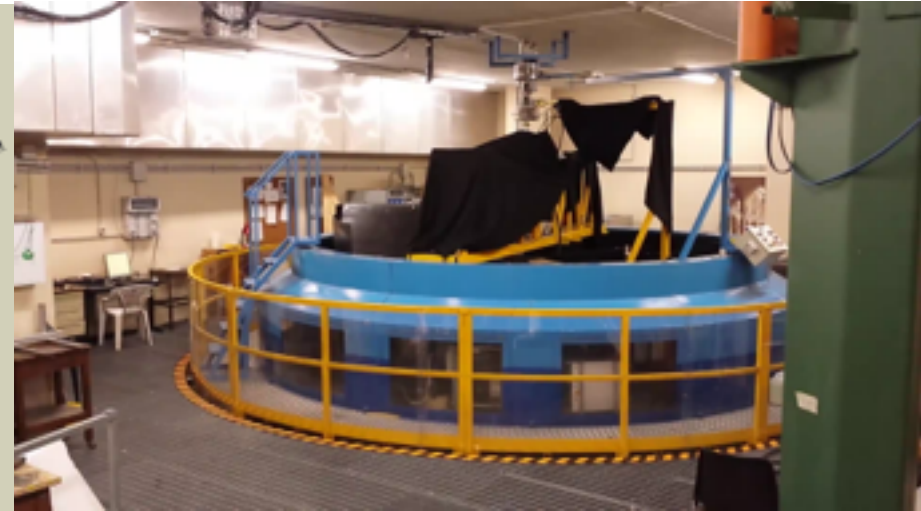
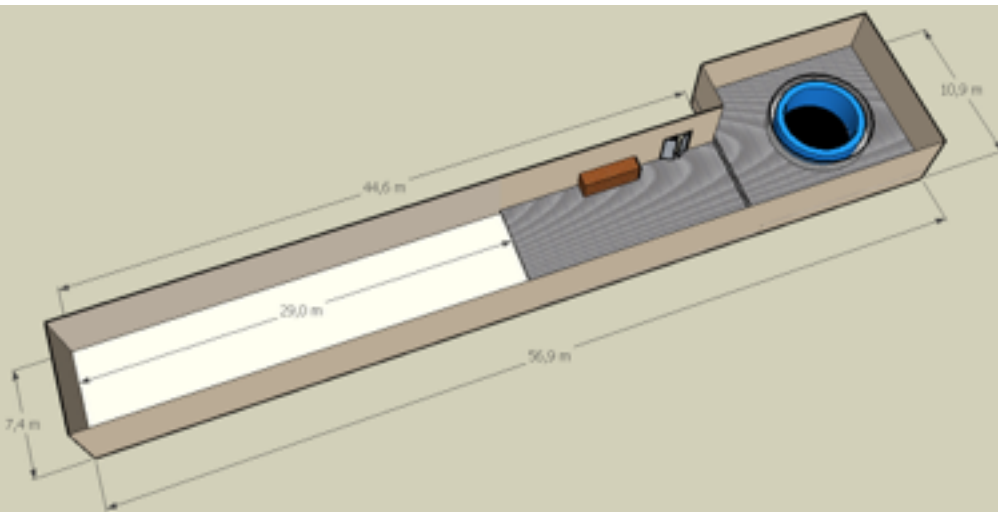
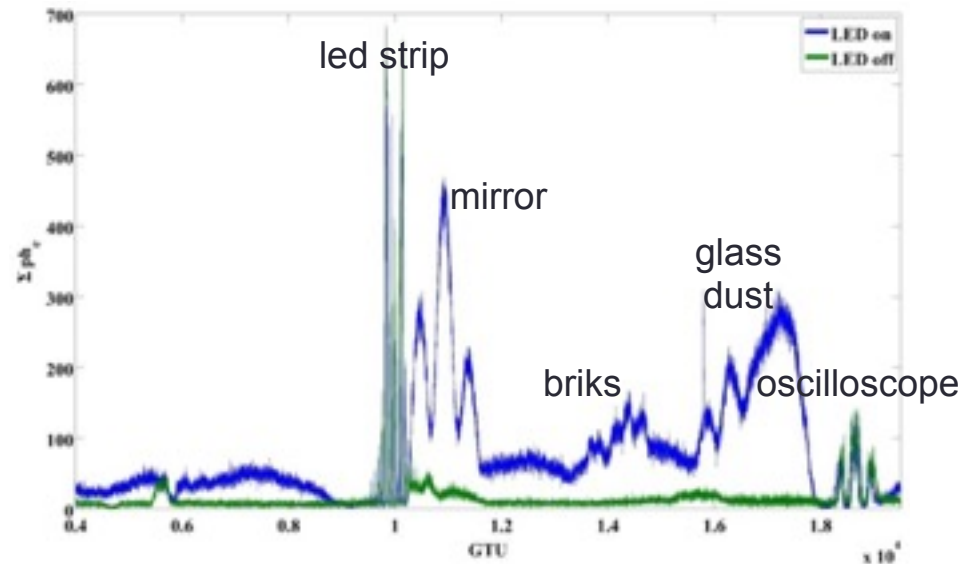
- 1st TL implemented in **FORTRAN**, easy to: **read**, **debug**, **run** and **modify**.



- 1st TL also implemented in **VHDL** code to configure **FPGA**
- FPGA resources employed: 7%
- Cross check between VHDL and FORTRAN: same input → same output.

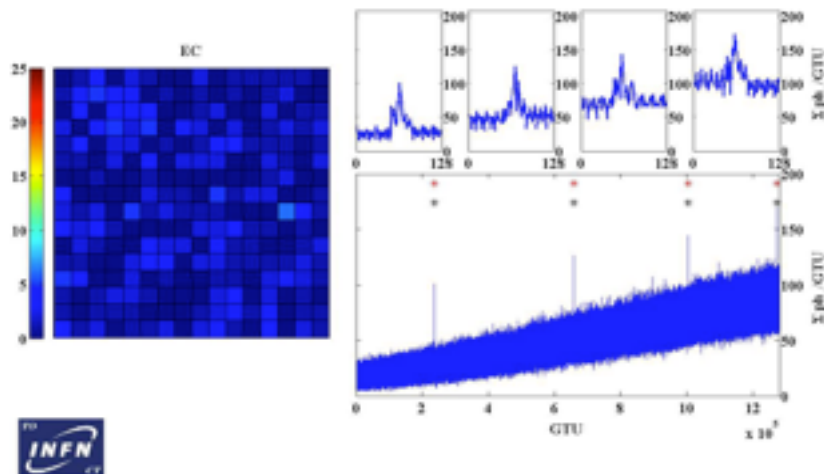
TurLab current setup

- Rotating tank replicates movement of FoV
- 5×5 pixels MAPMT
- One lens
- Light sources
- Different albedo materials
- electronics

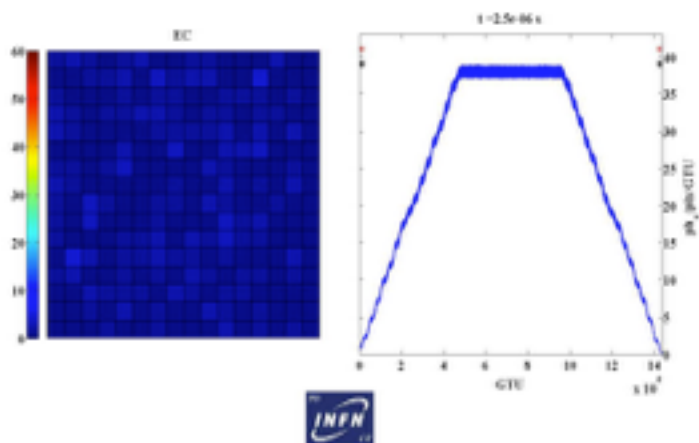


TurLab replicas

[cts]

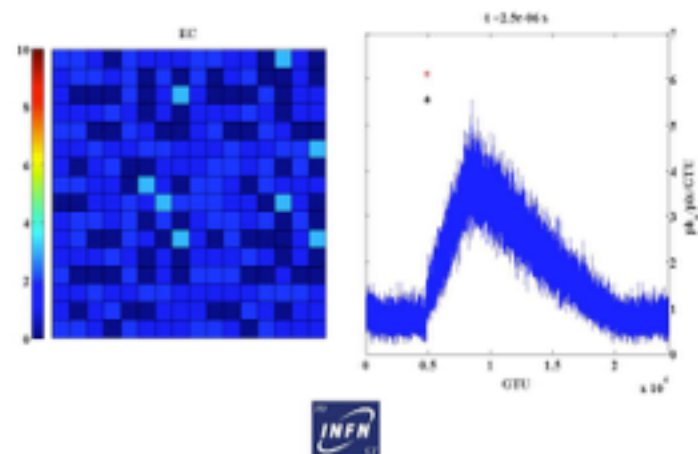


Cosmic Ray



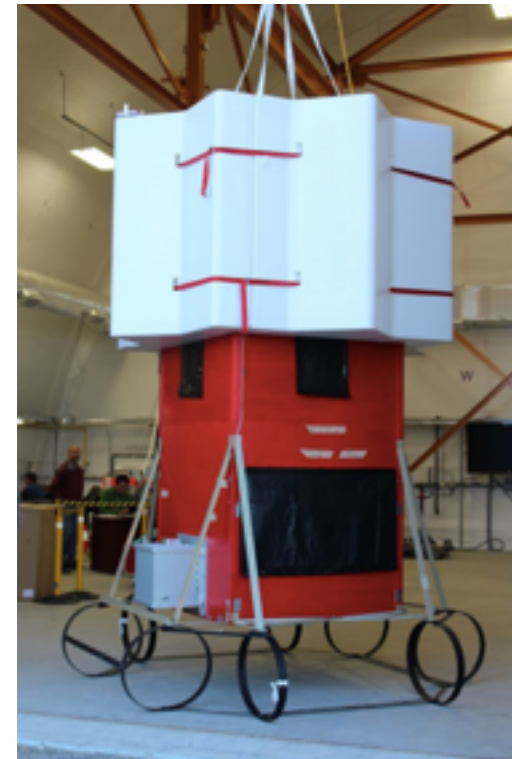
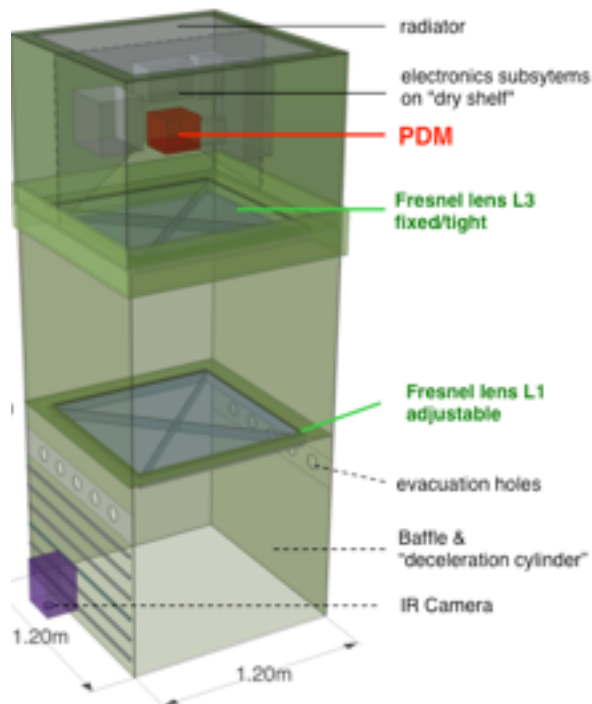
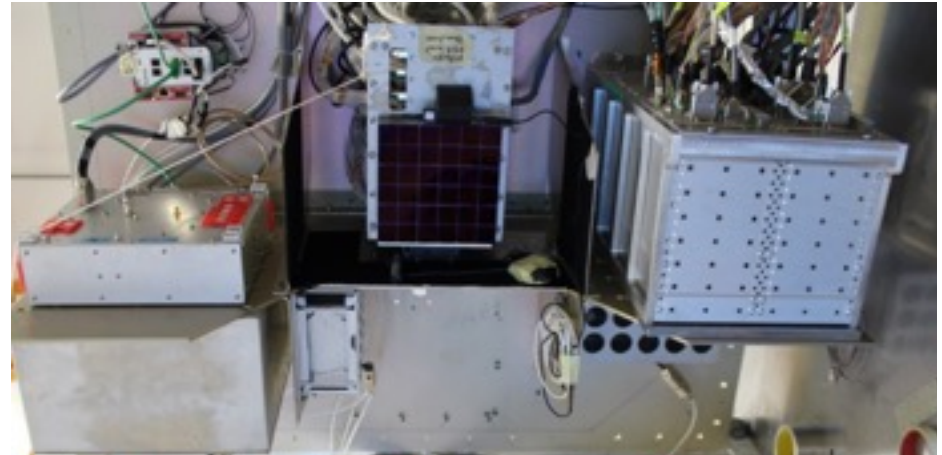
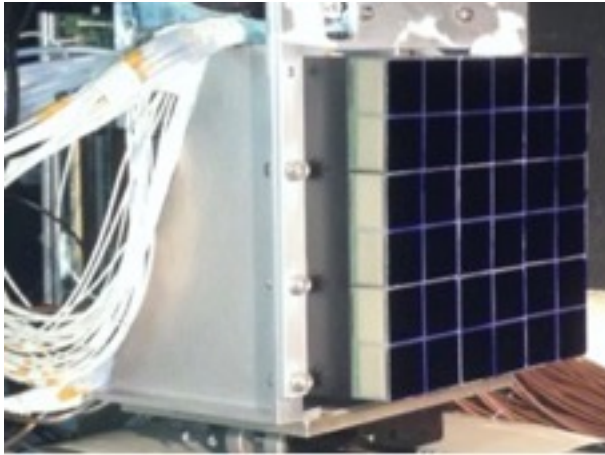
Transition over a city

[cts]

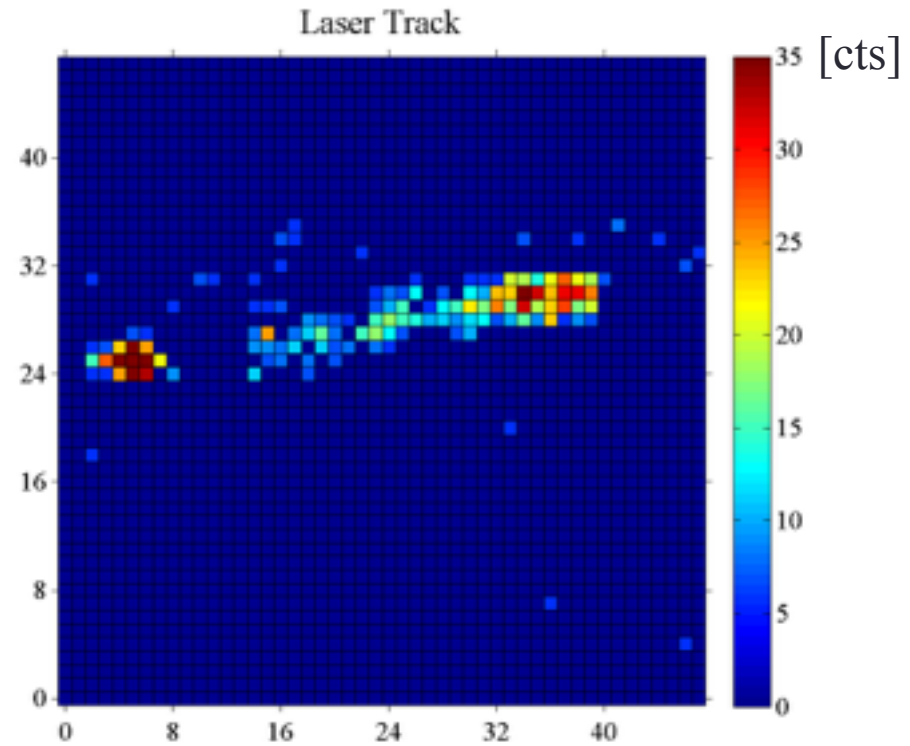
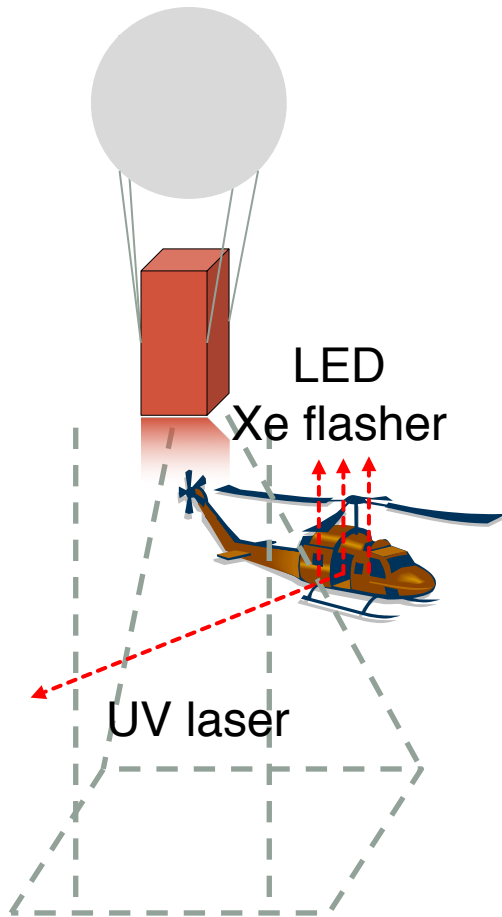


Lightning

EUSO-Balloon



EUSO-Balloon



UV light sources:

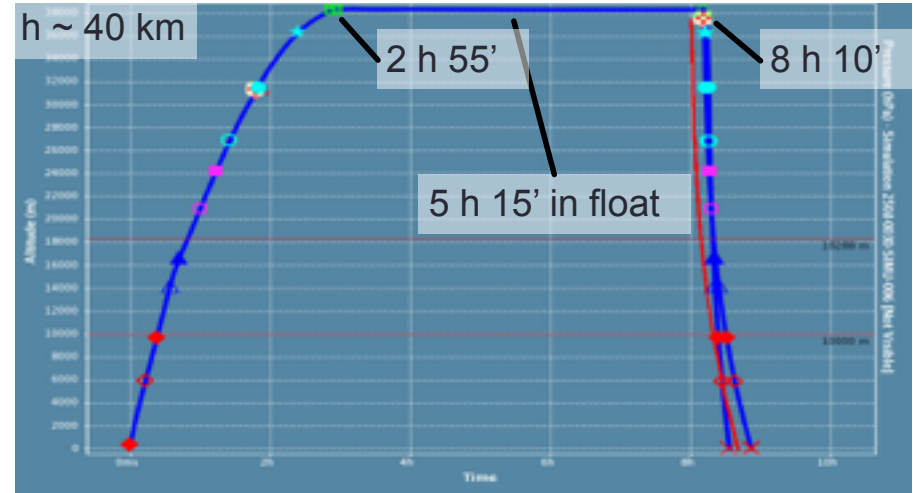
- **LED:** pointed directly to detector
- **Flash:** pointed directly to detector
- **UV Laser:** laser pulsed across FoV
- 5 mJ Laser $\sim 10^{20}$ eV CR



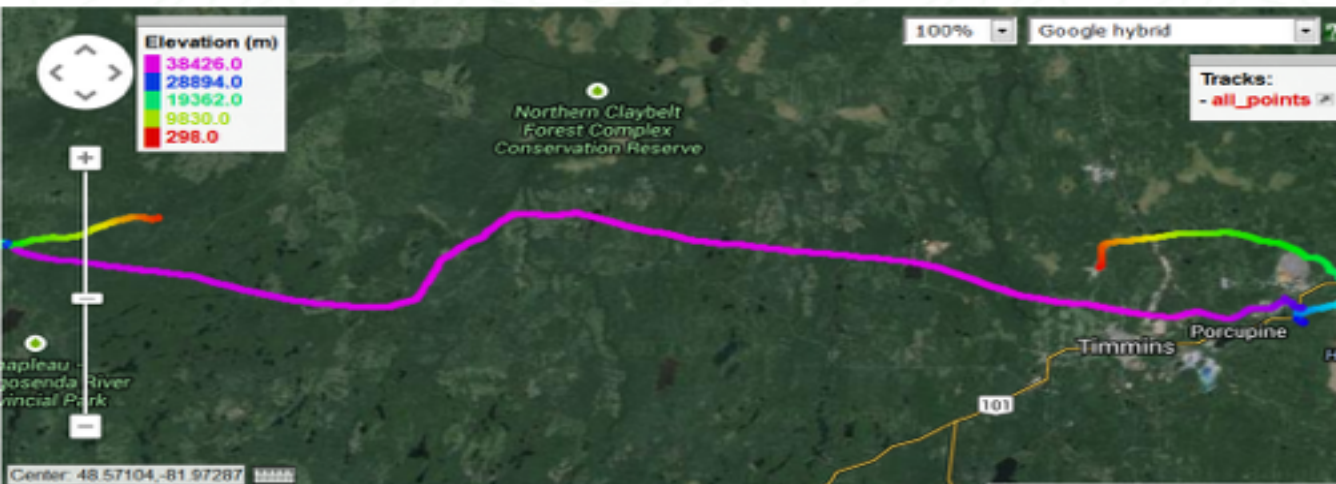
EUSO-Balloon flight



Date of flight: 08/25/2015



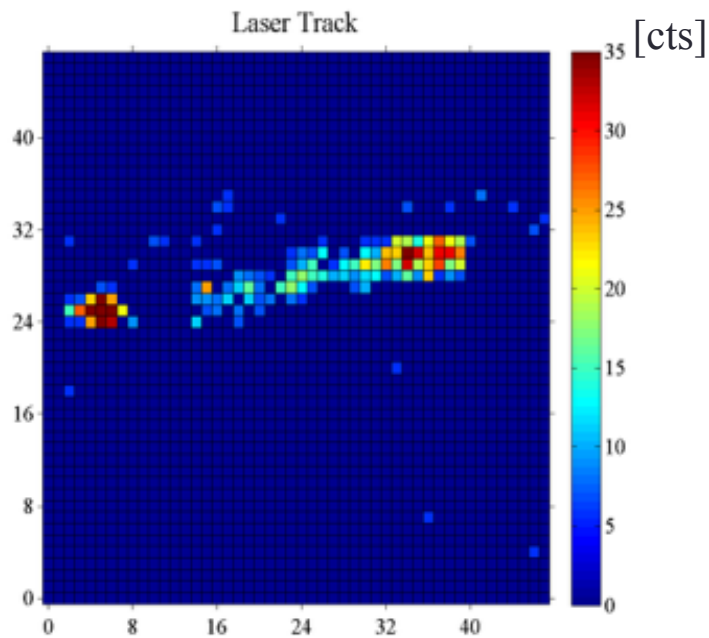
Vertical profile of the 9 hours flight of EUSO-Balloon



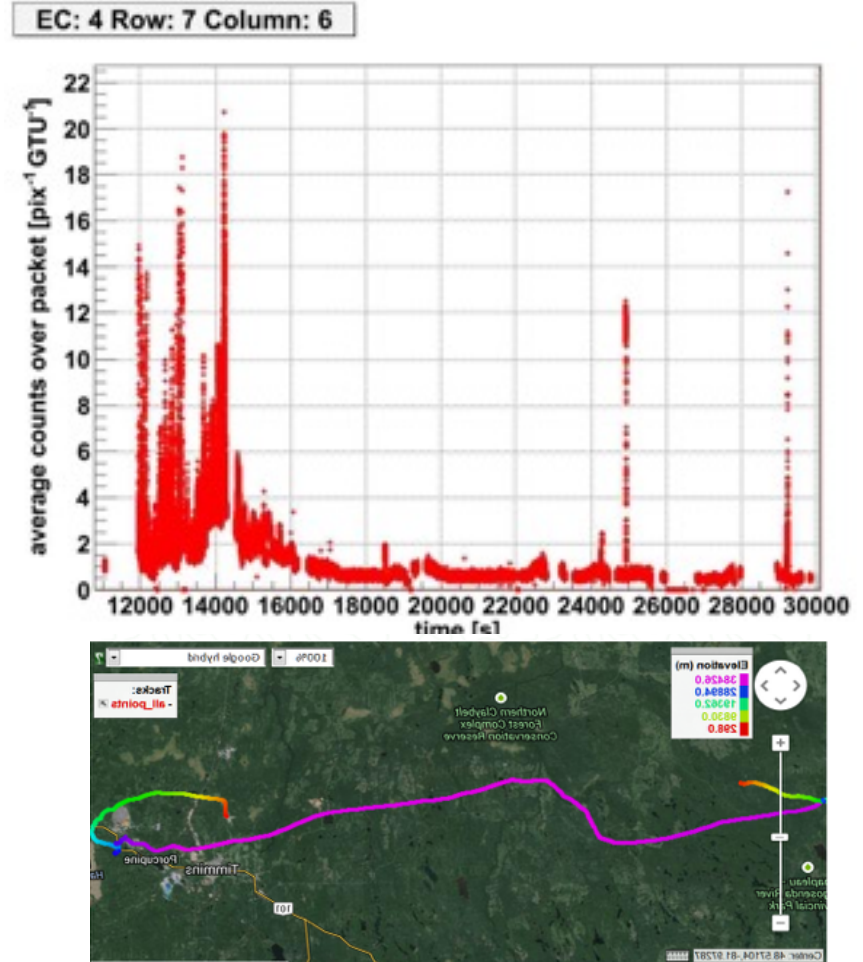
Horizontal profile of the 9 hours flight of EUSO-Balloon



Data from PDM and IR camera



Laser track as detected by the PDM



Evolution of one pixel during the entire flight

Trigger conditions

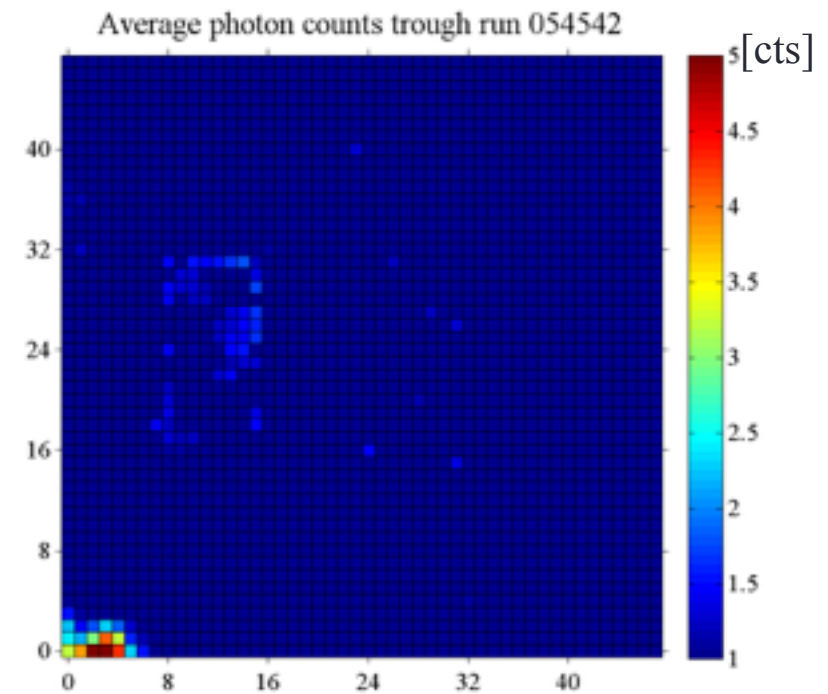
BCKG conditions:

- Ground light sources
- Background fluctuation
- Balloon rotation movement

Data taking conditions:

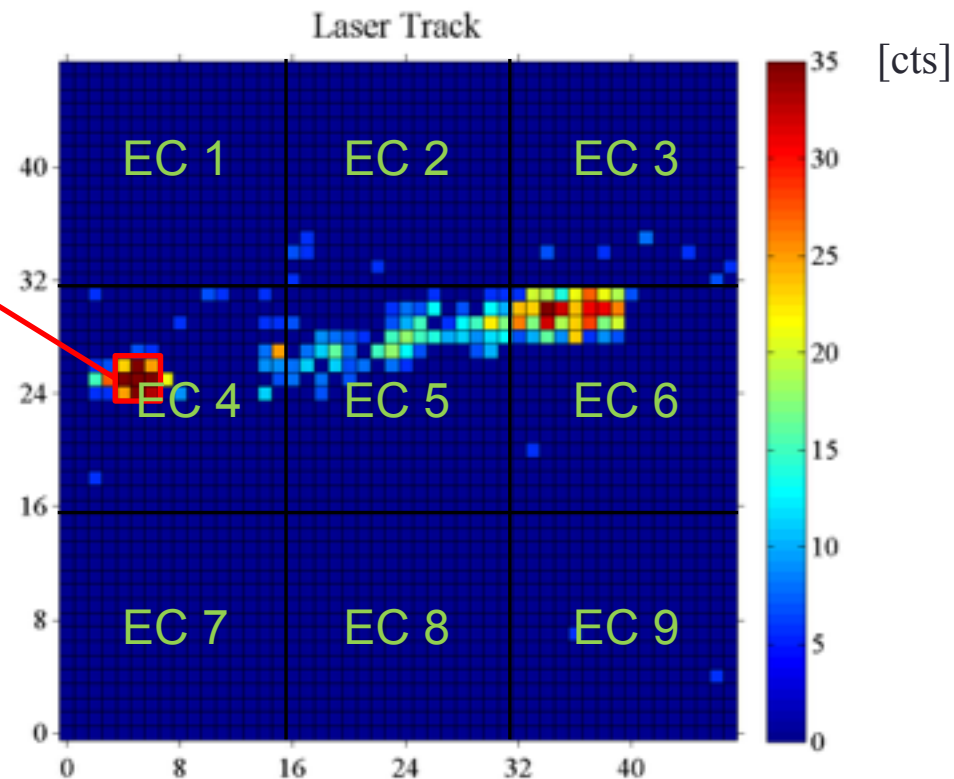
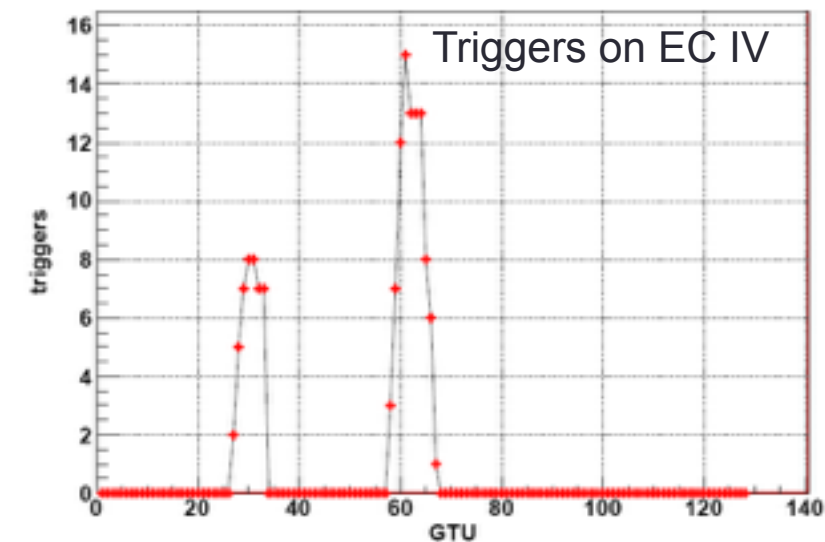
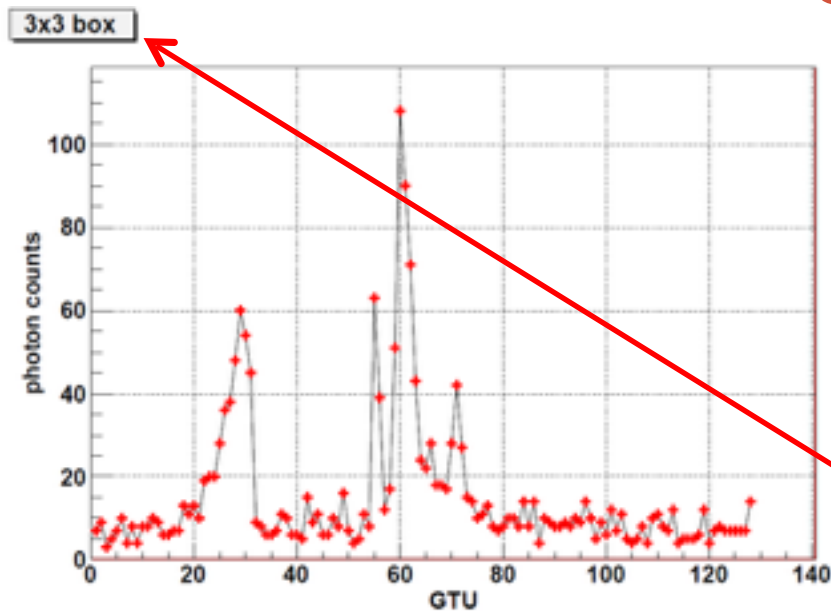
- GPS synchronization between helicopter and balloon (not working the night)
- Taking 128 GTU packets with 20 Hz rate, a problem for our thresholds algorithm

Most serious problems: balloon rotation and delay from packet to packet



First check of trigger response

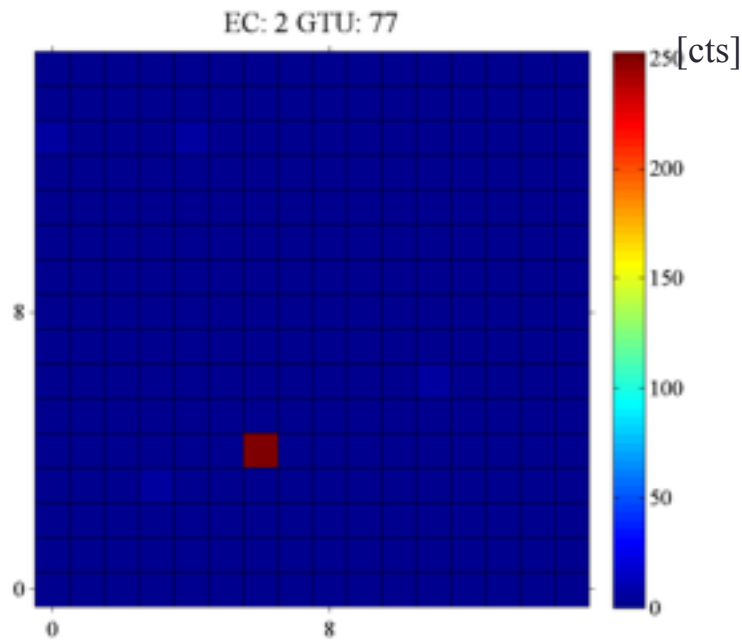
Evolution through the entire run of counts on the 3×3 box centered on the most counting pixel.



Triggers on EC 4 as a function of time.

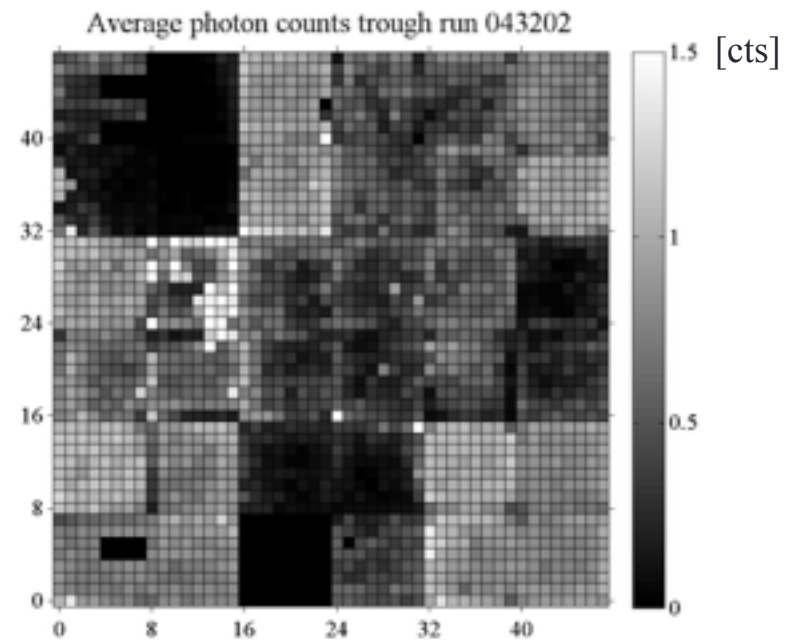
Problems with raw data

Out of control pixels



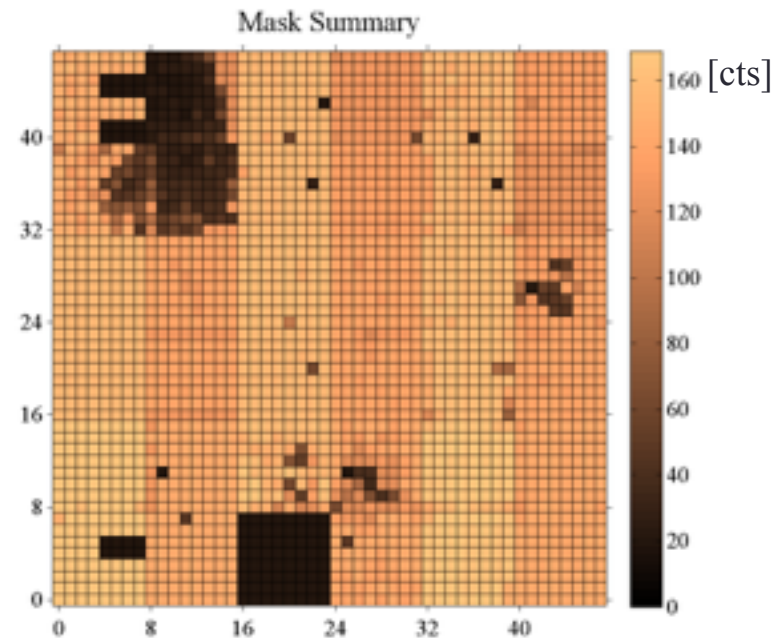
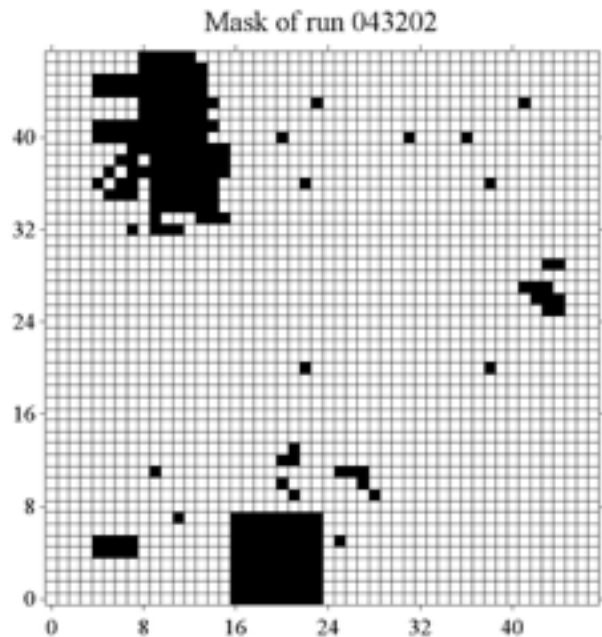
- Isolated pixels, in some GTUs, give us a lot of photon counts.
- This number is not due to light source
- It is a problem for the trigger logic

Low efficiency areas



- Some pixels of the EC have very low gain
- BCKG on 2×4 boxes is underestimated

Our solution: the mask



We generate a mask to:

- Remove all the pixels that give too many counts
- Do not count turned off pixels in the 2×4 average threshold algorithm to calculate a more reasonable BCKG



1st TL performance

041731 – 052559 (dark BCKG)

Run	Trigger	Laser	Other sources
041731	16	14	2
042351	1	1	0
042407	15	14	1
042614	3	3	0
042806	9	0	9
042957	9	7	2
043147	0	0	0
043202	20	18	2
043401	5	2	3
051610	25	24	1
051805	7	5	2
051959	6	5	1
052152	15	10	5
052344	1	1	0
052358	38	19	19
052559	14	5	9
	184	128	56

$$\nu = \frac{56}{8,5s} \approx 6,6 \frac{Hz}{PDM}$$

052753 – 254542 (very noisy BCKG)

Run	Trigger	Laser	Other sources
052753	199	29	170
052945	272	14	258
053139	29	0	29
053154	141	15	126
053352	283	6	277
053550	101	23	78
053743	167	5	162
053936	43	2	41
053951	221	14	207
054152	93	9	84
054348	272	21	251
054542	269	11	258
	2090	149	1941

$$\nu = \frac{1941}{6,5s} \approx 300 \frac{Hz}{PDM}$$



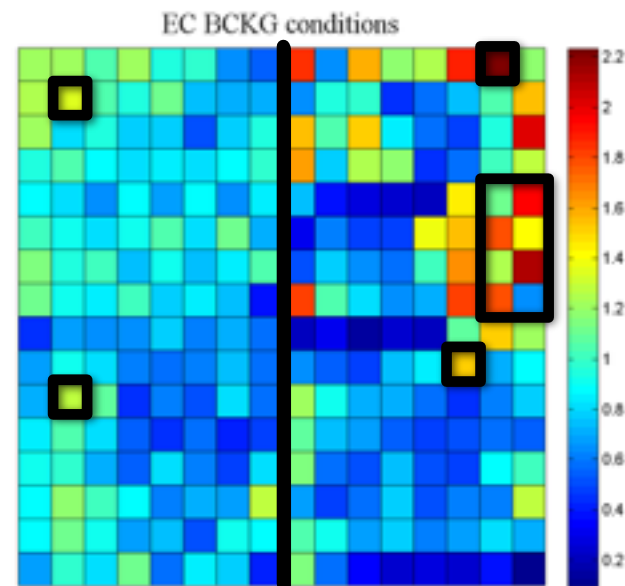
BCKG calculation using single pixel

Thresholds:

- Calculated using single pixel average over 128 GTU
- Settled at MAPMT level

Using “2×4” Algorithm:

- BCKG: 1,5
- n^{pix} : 2
- n^{box} : 53



Using “Single pixel” Algorithm:

MAPMT	BCKG [$\text{phe} \cdot \text{pix}^{-1} \text{GTU}^{-1}$]	n^{pix}	n^{box}
Top left	1,3	2	45
Top right	2,2	3	62
Bottom left	1,3	2	45
Bottom right	1,5	2	53

“Single pixel” algorithm performances

041731 – 052559 (dark BCKG)

Run	Trigger	Laser	Other sources
041731	12	11	1
042351	1	1	0
042407	15	15	0
042614	3	3	0
042806	0	0	0
042957	9	7	2
043147	0	0	0
043202	20	19	1
043401	3	3	0
051610	24	23	1
051805	4	4	0
051959	6	5	1
052152	13	10	3
052344	1	1	0
052358	23	19	4
052559	9	5	4
	143	126	17

$$v = \frac{17}{8,5s} \approx 2,0 \frac{Hz}{PDM}$$

052753 – 254542 (very noisy BCKG)

Run	Trigger	Laser	Other sources
052753	32	29	3
052945	20	14	6
053139	1	0	1
053154	36	14	22
053352	8	6	2
053550	27	23	4
053743	10	5	5
053936	3	1	2
053951	15	14	1
054152	12	9	3
054348	29	21	8
054542	14	12	2
	207	148	59

$$v = \frac{59}{6,5s} \approx 9,1 \frac{Hz}{PDM}$$

“2×4” vs “Single Pixel”

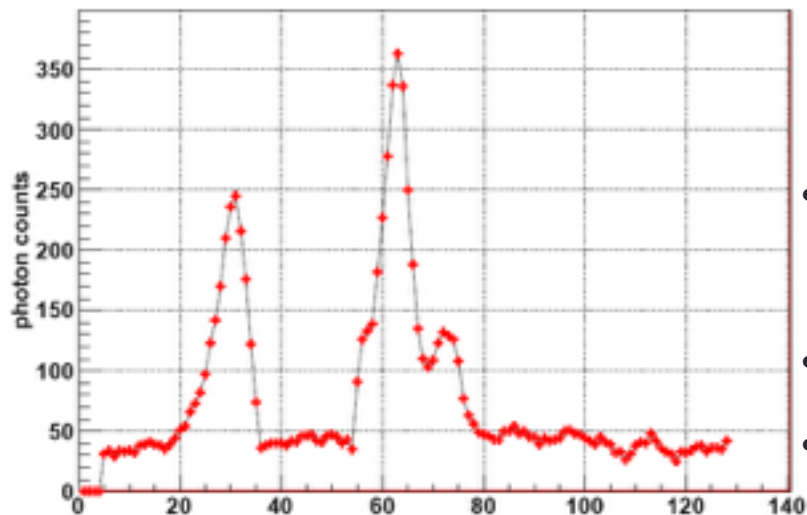
Version	Dark BCKG	Ground light source	Total
2×4	128	149	277
Single pixel	126	148	274

sample	$N_{2\times 4}$	N_S	$N_{2\times 4} - N_S$	$(N_{2\times 4} - N_S) / N_{2\times 4}$
All	105129	82314	22815	0,22
STD BCKG	28660	24902	3758	0,13
VN BCKG	76469	57412	19057	0,25

There is a 13% loss of triggering boxes as a result of setting thresholds at MAPMT level according to the highest BCKG value on the MAPMT.

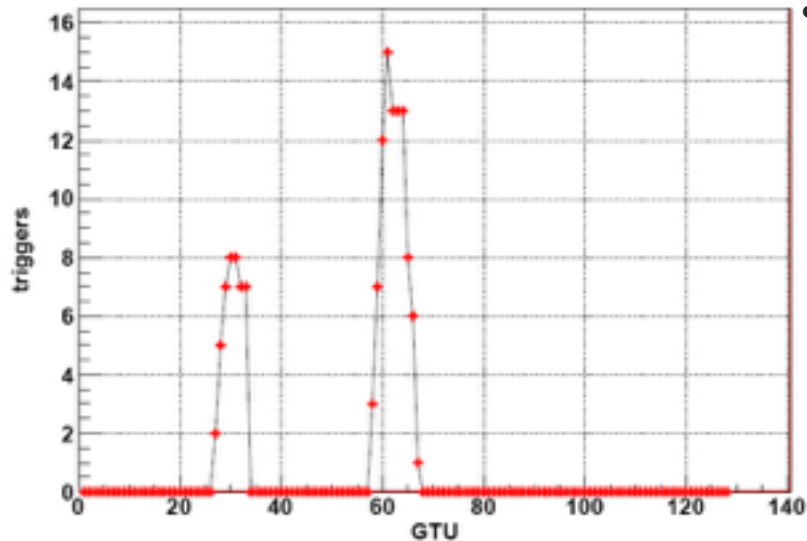
Energy Threshold

sum over 5 GTU on 3x3 box



- Average **signal** on which the trigger shoot: 81 ± 13 counts
- Average **noise** on relative 33 box: 39 ± 1 counts
- Average **ratio** between the signal and the noise: 2.1 ± 0.3
- This kind of signal excess is expected in a CR event with $E \sim 5 \times 10^{18}$ eV

Old trigger algorithm



Conclusions

- The 1st TL of JEM-EUSO was tested at TurLab and using EUSO-Balloon data.
- The original version of the 1st TL was successful triggering on:
 - Replicas of cosmic ray events at TurLab (performed using Arduino platform)
 - Laser events of EUSO-Balloon
- Data from EUSO-Balloon shows too high rate of triggers due to:
 - strong non-uniformity of pixel response,
 - Electronic noise,
 - Not suitable definition of BCKG level.
- “Single Pixel” version of 1st TL implemented:
 - It allows the correct BCKG calculation algorithm,
 - Rate of triggers on laser events decrease of 13%.

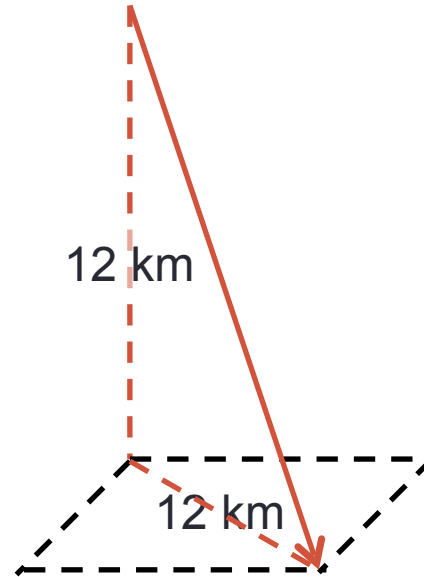
Next steps

- Current version of VHDL code employs the 11% of FPGA resources, modifications will be implemented to decrease this use and to better fit with specific FPGA
- Going to test at TurLab an EC similar to balloon one as a part of Eu-HIT project:
 - “Detection and Imaging of turbulent states of ocean and atmosphere by means of a JEM-EUSO-like detector at the TurLab facility (EUSO@TurLab)”.
 - Responsible: Dr. Sylvie Dagoret-Campagne Laboratoire de l'Accelérateur Lineaire, Université Paris Sud-XI
- In next months I will continue those activities with EUSO-Balloon data during an Erasmus Traineeship in Laboratoire de l'Accelérateur Lineaire, Université Paris Sud-XI.

Thank You!!!

- Publications related to my work:
 - M. Bertaina,..., G.Suino,..., for the JEM-EUSO Coll.: "EUSO@TurLab: An experimental replica of ISS orbits" EPJ Web of Conferences, Vol. 89, pag. 03003 (2015)
 - G. Suino et al. for the JEM-EUSO Coll.: "Test of JEM-EUSO 1st level trigger using EUSO-Balloon data", Proc. 34th International Cosmic Ray Conference, Den Haag, 29 Jul - 6 Aug 2015.
 - G. Contino, G. Suino, et al. for the JEM-EUSO Coll.: "The EUSO@TurLab project", Proc. 34th International Cosmic Ray Conference, Den Haag, 29 Jul - 6 Aug 2015.

Lifespan of a CR signal in an EC



$$\Delta t = 2 \frac{12 \text{ km}}{0,75 \frac{\text{km}}{\text{GTU}}} = 32 \text{ GTU}$$

$$\Delta t = \frac{12 \text{ km}}{0,75 \frac{\text{km}}{\text{GTU}} \tan\left(\frac{\pi/4}{2}\right)} = 39 \text{ GTU}$$

$$\Delta t = \frac{12 \text{ km}}{0,75 \frac{\text{km}}{\text{GTU}} \tan\left(\frac{\pi/2}{2}\right)} = 16 \text{ GTU}$$

$$\Delta t = \frac{\Delta s [\text{km}]}{0,75 \left[\frac{\text{km}}{\text{GTU}} \right] \tan\left(\frac{\vartheta}{2}\right)} = [\text{GTU}]$$



Preliminary helicopter triggers

Run			EC-II			EC-V			EC-VI			EC-VIII			EC-IX			Helicopter			
Type	number	packet	...	gtu	x	y	...	gtu	x	y	gtu	x	y	...	gtu	x	y	gtu	x	y	
CPU	052344	84		24	17	43		20	25	25	19	35	22		24	30	13	21	33	14	Y

A laser event is typically characterized by few ECs triggering almost in time.

In the table we reported:

For each **packet** and **EC** where a trigger occurs, the **position of the 3×3 cell** which gave the maximum signal excess and the relative **GTU**.

Founded around 240 laser events

Still remaining some false trigger!



“Single pixel 2 GTU” algorithm features

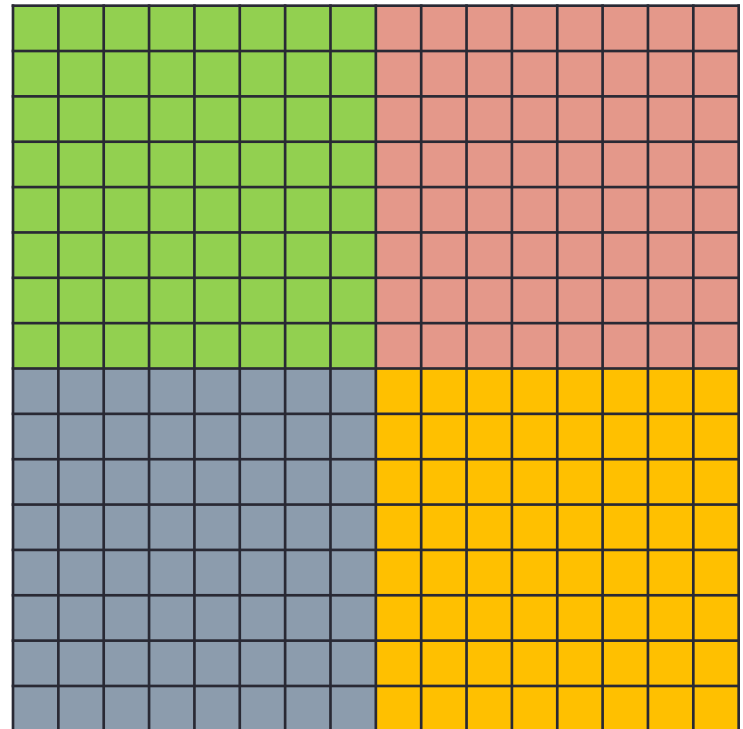
Check:

- done on the summation of counts of 3×3 boxes **over 2 consecutive GTU**

$$\sum_{i=1}^{\textcircled{2}} \sum_{3 \times 3} N \geq n^{box}$$

Thresholds:

- Calculated using single pixel average over 128 GTU
- Settled at MAPMT level



“Single pixel 2 GTU” algorithm performance

041731 – 052559 (dark BCKG)

RUN	trigger	true	?
041731	13	11	2
042351	2	1	1
042407	14	14	0
042614	3	3	0
042806	0	6	0
042957	8	5	3
043147	0	0	0
043202	18	18	0
043401	2	2	0
051610	26	25	1
051805	5	5	0
051959	6	5	1
052152	13	10	3
052344	1	1	0
052358	22	18	4
052559	10	5	5
	143	129	20

$$\nu = \frac{20}{8,5s} \approx 2,4Hz$$

052753 – 254542 (very noisy BCKG)

RUN	trigger	true	?
052753	33	27	6
052945	27	15	12
053139	1	0	1
053154	21	13	8
053352	9	6	3
053550	30	24	6
053743	8	5	3
053936	2	2	0
053951	16	14	2
054152	13	9	4
054348	27	21	6
054542	16	12	4
	203	148	55

$$\nu = \frac{55}{6,5s} \approx 8,5Hz$$